

da Vinci Gear Machine

for the da Vinci Gear Challenge by
GrabCAD and Stratagems Education

Designed by Clint K. Campbell

SUMMARY

Thank you for your interest in my design!

This documentation covers all aspects of my design for the da Vinci Gear Challenge. I had a lot of fun designing it, and I hope that you find it just as entertaining as I did.

DESIGN ORIGIN

The concept for my design is based on the image displayed within the Challenge itself.

<https://grabcad.com/challenge/mile-de-vinci-gear-challenge/>, along with a handful of images downloaded from sources with larger, more detailed images of da Vinci's drawing.



Part of the Challenge's requirements were to "Consider the ways in which 3D printing differs from Renaissance era fabrication technologies and adjust the designs accordingly." I see no reason to adhere to da Vinci's pen-based design, since modern technology provides much better mechanical solutions. However, I did want my design to closely resemble da Vinci's original drawing, simply for aesthetic appeal and overall recognizability.

I also opted not to use da Vinci's original one-way gear mechanisms, since I did not want my design to click on it rotators. My design includes a positive 'stop-dutch' of sorts, to allow (and/or limit) rotation in either direction... with no disassembly clicking.

My personal 3D printing experience has been limited to FDM, thus far... so my design is engineered for that flavor of additive manufacturing. Specific print settings will be detailed later in this document. However, I will note that this design requires zero support material and zero post-

assembly method is a consideration. Large losses were used, whenever possible, to help with build surface adhesion. However, I also tried to avoid large areas of base layer material, to minimize warping...and I attempted to do this while using features that looked integral and appealing to the design.

Ironically, I chose **de Wind La Pro from BZ Printing...** as my original design included tolerance values for that printer (with the default 0.2mm nozzle). Also ironically, my 3d printer developed a mechanical issue at the extruder, which I was unable to repair (or modify to an upgraded extruder design, more accurately).

Because of this technical difficulty, I was forced to use the **LulzBot TAZ 3** where I work. (Yes, I use the term 'forced' quite frequently.) However, this meant that I was forced to adjust my tolerances on many parts to accommodate TAZ's long 0.4mm nozzle. (In that sentence, the word 'forced' was much more literal.)

The entire design was modeled using **TurboCAD v10**, in native file format... then exported into STL, STEP, IGES, and OBJ formats. (I exported OBJ files for use in constructing an 'Assembly and Operation' video, which can be viewed at: <https://youtu.be/2W2P886-0C20u2>)

TECHNICAL SPECS

- 1) Part count: 46
- 2) Print settings (LulzBot TAZ 3 w/ 0.4mm nozzle):
 - a. Layer height: 0.2mm
 - a. Shell thickness: 1.2mm
 - a. Top/bottom thickness: 1.2mm
 - a. infill density: 20%
 - a. Print speed: 30mm/sec
 - a. Filament:
 - 1. green 'Husky Silver' PLA from **DrB Polymers** (silver parts)
 - 2. green 'Black Red' PLA from **DrB Polymers** (black parts)

EXTRA LIST

PART NAME	FILE NAME	VOLUME
1) Stand	Stand_ fused.STL	13.754g 30"
2) Left gear	Gear left_ fused.STL	16.474 30"
3) Right gear	Gear right_ fused.STL	16.469 30"
4) Central gear	Central gear_ fused.STL	5.9984 30"
5) Pinch shaft	Pinch_ fused.STL	5.4755 30"
6) Axle	Axle_ v1_ fused.STL	1.4069 30"
7) Carrier	Carrier_ fused.STL	7.3396 30"
8) Ratchet	Ratchet_ fused.STL	1.3374 30"
9) Ratchet Handle	Ratchet_Handle_ fused.STL	6.6497 30"

- 4) Once you are satisfied with the fit, snap the Pin at Retaining Clip onto the end of the Pin at shaft. The top of the Clip should rest inside the left side of the Stand to prevent the Clip from rotating with the Shaft.  The clip will require a bit of pressure in order to push onto the end of the Pin at shaft.
- 5) Lower the Control Gear into position by rotating the Left and/or Right Gears, then insert the Axis through the front of the Stand and through the Control Gear, until it comes to rest inside the Center. For best operation, use graphite to lubricate the inside of the shaft opening in the Stand, and a small area of the Axis shaft, directly behind the "spool" portion, and the end section of the Axis shaft.

The Control Gear will need to be rotated until the tapered spine of the Axis clips into one of the six notches in the Control Gear.

- 6) Test the rotation of the gears. They should mesh snugly, yet rotate smoothly. If not, you may need to make adjustments with a razor, sandpaper, et cetera.
- 7) Once you are satisfied with the fit, insert the Axis Retaining Clip into the slot at the top of the Center, and snap it onto the Axis.  The clip has a beveled side, and needs to be oriented with the beveled side of groove of the Axis. The clip will require a bit of pressure in order to push onto the end of the Axis.
- 8) Slide the shaft of the Ratchet into the hole at the front of the Stand, from the left side. The Ratchet has three spring-loaded arms, but only one of those arms has detents that mesh with the notched rim in the Stand. These detents should face downward. For best operation, lubricate the small diameter of the shaft with graphite, as well as the shaft opening in the Stand.
- 9) Push the Ratchet Handle onto the beveled end of the Ratchet's shaft. It should click snugly into place.

I also designed a slightly redundant Ratchet Handle Clip to ensure that the Ratchet Handle stayed secured to the Ratchet.

If you choose to use it, insert the forked end into the rectangular opening at the end of the Ratchet's shaft to gently



NOTE: The top of the shafts require quite a bit of force in order to seat properly inside the Hatcher's shaft.

- c) Place the Handle Arm onto the Pivot shaft by placing the rounded retention lug into the square opening at the end of the Pivot. Then, snap the Handle Clip into the Pivot and around the Handle Arm. The clip will require quite a bit of force, and will snap into place with a solid click.



- d) Insert the small peg of the Handle into the hole at the end of the Handle Arm, then secure by snapping the Handle Retaining Clip over the end of the Handle. You may wish to lubricate the small peg with graphite, as well as the peg opening in the Handle Arm. **NOTE:** The clip has a beveled side, and needs to be oriented with the beveled side of groove of the Handle. The clip will require quite a bit of force in order to snap onto the end of the Handle.

- e) Tie a length of string around the "Spool" of the Axis, towards either the front of the threads, or the rear. Secure the string with a small dab of 1-minute epoxy, or adhesive of your choice. Allow the adhesive to cure.
- f) Wrap the string around the "Spool" several times, following the small threads... which I added could be nice, neat spacing of string.
- g) Tie a weighted object to the base end of the string. Enjoy lifting and lowering the object.

Assembly is completed

You may also refer to my brief Assembly and Operation animation video at <https://youtu.be/2088i2G285s> for further reference.

NOTE: All parts of my printed parts fit together perfectly. Due to limited time, I had to use lower quality print settings than I generally use. Due to this, the top of the vertical holes did not print perfectly (as I suspected), but were quite good enough to allow assembly without any processing.

OPERATION INSTRUCTIONS

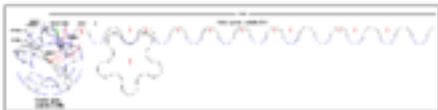
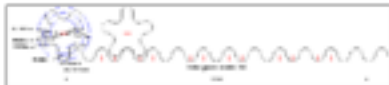
- c) The handle turns the Right Gear in whichever direction you crank it, while the Left Gear rotates in the opposite direction. My assembly was quite stiff after assembly, but loosened up after a bit of "breaking in" by manually rotating the gears. This is why I suggest using graphite lubrication on all of the shafts and their respective openings.

The flatshat operates by applying pressure against the circumference of the main gears as they rotate, causing them to stop when rotated against the cam-style flatshat arm. It may work "as is", or it may need a light coat of rubber cement applied to the surfaces that contact the main gears. In order to do this, you will need to remove the flatshat from the stand, and allow the cement to fully cure before reassembling.

Depending on your print settings/quality, it may also be necessary to coat the outer circumference of the Left and Right Gears with rubber cement. My flatshat design requires friction between the main gears and the arms of the flatshat... otherwise, it will not function.

THE DESIGN

As soon as I saw this design challenge, I knew that I had to enter it... and what I wanted to do. So I set up the parameters of the gear mechanism using these drawings:



This gear design mimics de Vries's original drawings, while using much more modern design theory and fabrication technology. Technically speaking, de Vries's drawings are wrong. The large diameter of the outer gears produces a very high gear ratio with the center gear, which creates higher rotational speed...and much more importantly, increased torque requirements...in order to lift the load that is suspended from the spindle. As a former crane operator and someone who designs and machines loads for a living, I knew this before starting my design. But I wanted to keep my design reminiscent of de Vries's drawings.

- ④ The Axis Retaining Clip has a beveled side cut. This is due to the orientation of the Axis during printing... which involves a 45° slope in order to print successfully.
- ⑤ The Pivot Retaining Clip has a beveled side, which mates with the Pivot without much logic involved. It only fits one way, and it is quite obvious. The Pivot is printed in an orientation that requires steps, in order to print correctly... thus, the clip shares that geometry.
- ⑥ The Handle Retaining Clip also has a beveled side, which mates with the Handle. The Handle is printed in an upright position that required me to design it with a base in the groove that holds the Retaining Clip.
- ⑦ The Ratchet Handle Retaining Clip is a very redundant part, as the Ratchet Handle fits onto the shaft of the Ratchet in a very perfect way. If you choose to use this part, it will require an enormous amount of pressure, but will eventually snap in place, and sound like it broke. (Your right? Mine did not... but it scared me.)

POLITICALLY CORRECT ENDING

This design is not perfect, by any means. Generally speaking, I have a month or two to test and prove my designs (which I work on almost constantly). I have challenges like this, because they test my ability to work on yet another project... with yet another timeframe to schedule around my work schedule. I work best under stress... however, I don't see time constraints as an issue, anymore.

As one of my co-workers always says, "Quality, or Production. Choose one. You can never have both at the same time."

Given enough time, my design would work flawlessly. That's what I do for a living. I design things... machine things... and make adjustments.

The flat side of the Carrier was intended to hold an entirely different "Ratchet" design, by the way. (And today, I'm thinking that design may have been the better option.)

CONCLUSION

My design looks great, as I finally view it in reality... gathering light and reflections in the PLA filaments that I chose to print the parts with. It's beautiful, yet slightly menacing... resembling a Gelling gun from the 21st Century. My maternal uncle told me, "Dad, if you don't win this challenge, those people are crazy." I'm not sure about that... there were a lot of good designs already posted, and I'm entering mine at the very last moment... [I'd love to stand by the old adage that "best comes last," but I don't subscribe to that line of thinking.

God bless every entrant to this Challenge, as they are all worth the prize. If nothing else, hopefully we all had fun doing it, and learned something.

Good night, and may the best design win.

A rectangular box containing a handwritten signature in black ink. The signature is cursive and appears to read "Gert R. Campbell".

Gert R. Campbell