

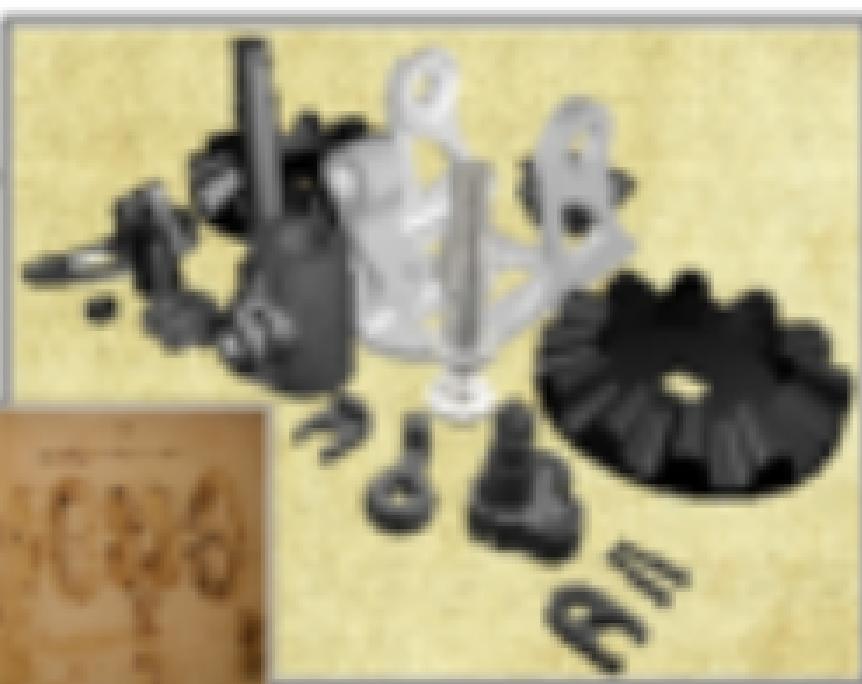
Thank you for your interest in my design!

This documentation covers all aspects of my design for the [dVinci Gear Challenge](#). I had a lot of fun designing it, and I hope that you find it just as interesting and did.

DESIGN DETAILS

The concept for my design is based on the image displayed within the challenge itself:

(Design, build, and testing mode) [challenge](#) along with a handful of images downloaded from sources with larger, more detailed images of dVinci's drawing..



Part of the Challenge's requirements is to "Consider the weight of each part by printing others from filament using fabrication techniques and adjust the designs accordingly." I was not sure to adhere to this rule but found some great tradeoffs in the parts that were printed in silver.

that I am "Husky" quite frequently.) However, this meant that I was forced to adjust my tolerances on many parts to accommodate the larger print size. (In their defense, the word "Husky" was much more liberal.)

The entire design was modeled using **Blender 2.80** and its native file format... then exported into STL, GCODE, and OBJ formats. (I imported OBJ files for use in constructing an Assembly and Operational video, which can be viewed at <https://youtu.be/gWtM1nqH0tU>.)

TECHNICAL SPECIFICATIONS

1. **Print material:** **PLA**
2. **Print settings (either <https://github.com/erikjordahl/PLA>)**
 - a. Layer height: **0.1mm**
 - b. Shell thickness: **0.4mm**
 - c. Top/Bottom thickness: **0.4mm**
 - d. infill density: **5%**
 - e. Print speed: **100mm/s**
 - f. Filament:
 - i. green "Husky Fiber" PLA from **Orb Polymers** (other parts)
 - ii. green "Work Net" PLA from **Orb Polymers** (Duct 3 parts)

All parts files have been rotated for proper printing orientation, centered on the Z axis, and are sitting on the Z plane. All files have been run through the [Model Router](#) service at [Tinkercad](#) (the default of the software), (thus the "Tinkercad [.STL]" name of all files). I believe that they are well designed and printable for most home printers.

All parts were designed to be printed without using support material, a left, or a build. However you may need support structures to the board part, due to the vertical holes. (My stand printed just fine without using support.)

Only one of each part needs to be printed. Due to my time frame, I used full infill for most parts, a layer height of 0.2mm, and a 0.4mm wall thickness. My temperatures were 230°C for the extruder, and 60°C for the build(BED) build surface. I used two different colors of print PLA from On3D Printers. My print speed was 100mm/s for all prints, in which each print had 100% infill.

ASSEMBLY INSTRUCTIONS:

- a) Position the Left Gear and Right Gear on either side of the Carrier, and hold them together while inserting them into the slot between the sides of the Stand. (The left gear



minish area of the Axle shaft, directly behind the "spur" gear box, and the end section of the Axle shaft.



The Control Gear will need to be rotated until the tapered spline of the Axle aligns with all the slots shown in the Control Gear.

- 6) Test the rotation of the gears. They should mesh tightly, yet rotate smoothly. If not, you may need to make adjustments with a wrench, sandpaper, etc., etc.
- 7) Once you are satisfied with that, insert the Axle Retaining Clip into the slot in the top of the Carrier, and snap it onto the Axle. [NOTE: The clip has a levered side, and needs to be oriented with the levered side of greatest of the Axle. This will require a bit of pressure in order to push onto the end of the Axle.]
- 8) Slide the shaft of the Bushing into the hole at the front of the Stand, from the left side. The Bushing has three spring loaded arms, but only one of these arms has detents which mesh with the slots cut into the Stand. These detents should face downward. For best operation, lubricate the outer diameter of the shaft with graphite, as well as the shaft opening in the Stand.
- 9) Hold the Bushing firmly in the hole and slide the Bushing into the Stand. It should snap

the handle assembly, and then slide the stringing tube onto the handle, as well as the peg opening in the Handle Arm. (See Fig.) The clip has a beveled side, and needs to be oriented with the beveled side of groove of the Handle. The clip will require quite a bit of force to enter it's slot into the end of the Handle.



- (e) Tie a length of string around the "Spool" of the kite, towards either the front of the Handle, or the rear. Secure the string with a small dab of quick-dry epoxy, or adhesive of your choice. Allow the adhesive to cure.
- (f) Wrap the string around the "Spool" several times, following the small threads... which I added just to nice, neat spacing of string.
- (g) Tie a weighted object to the free end of the string. Enjoy flying and towing the object.

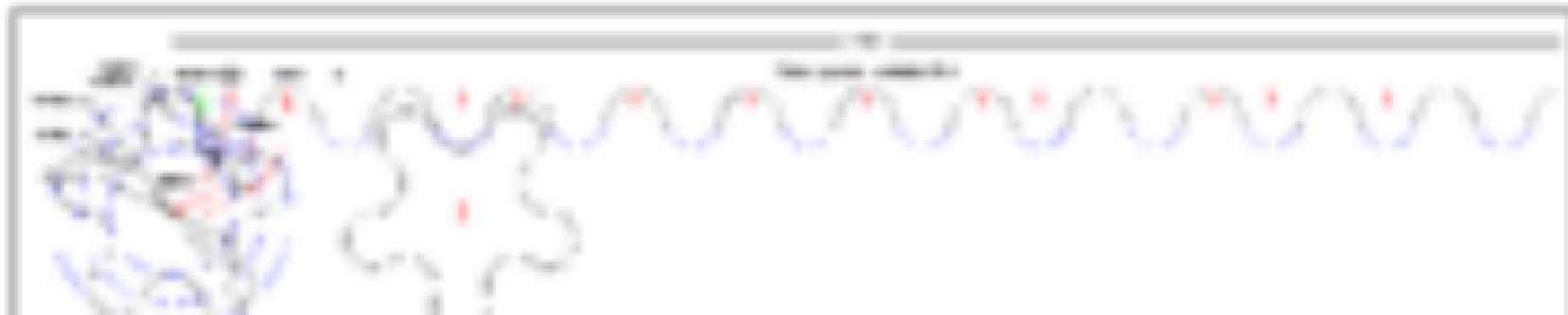
Assembly is completed!

You may also refer to my brief Assembly and Operation principle video at <https://youtu.be/xtHnRzLJXoU>, for further reference.

NOTE: All parts of my printed parts fit together perfectly.. Due to limited time, I had to print them in two pieces. The top part is the handle, and the bottom part is the handle arm. They are designed to be glued together.

Toolbox

As soon as I saw this design challenge, I knew that I had to enter it... and what I wanted to do. Here's all up the parameters of the gear necklace using these drawings:



- 4) The Bottom Handle Retaining Clip is a very redundant part, as the bottom handle fits onto the shaft of the Ratchet in a very perfect way. If you choose to use this part, it will require an enormous amount of pressure, but will eventually snap into place, and cause the Ratchet to break. (Your right hand... Mine did not... But I warned you.)

POLITICAL CORRECT ANSWER:

This design is not perfect, by any means. Currently speaking, I have a hard time finishing and presenting my designs (which I work on almost constantly). I have challenges like this, because they limit my ability to work on yet another project... nothing at present time allows me to schedule around my work schedule. I work best under stress... however, I don't see time constraints as an issue, anymore.

As one of my core values is always "Quality, or Production. Choose one. You can never have both at the same time."

Given enough time, my design would work flawlessly. That's what I do for a living. I design things... machine things... and make adjustments.

For the rest of the time, we produce to a strict deadline. That's how I do it.

